

# BS 24V DOUBLE SHAFT MOTOR - 36.4800.0000 BUILD-IN RECEIVER - ELECTRONIC LIMIT SETTING

### **TECHNICAL SPECIFICATION:**

- 24Vdc, 16Watt
- nom. 0.8Nm max. 1.0Nm
- 34 rpm
- max. running time 7 min.
- max. curtain weight 4 kg
- max. 5 cord rolls
- has to be used with Multi remote and/or Multi wall switch RF
- only to be used in Forest BS system and with Forest power supply for BS motor



WARNING: WHEN USING THE QUICK LOCK CORD ROLL, BE SURE TO LOCK THE CORD BEFORE USING THE MOTOR

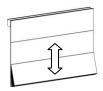
## PROGRAMMING REMOTE TO BS MOTOR

first select the desired channel

switch on power to the motor:



motor will jog to acknowledge:

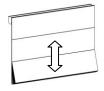


within 10 seconds after jog, press P button and press OPEN button on remote





motor will jog to acknowledge:



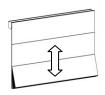
### REMOVE PROGRAMMED CHANNEL

first select the desired channel

switch on power to the motor:



motor will jog to acknowledge:



within 10 seconds after jog, press P button and press STOP button on remote





motor will jog to acknowledge:



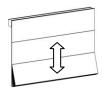
### **CHANGE MOTOR DIRECTION**

first select the desired channel

switch on power to the motor:



motor will jog to acknowledge:

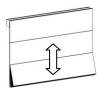


within 10 seconds after jog, press P button and press CLOSE button on remote





motor will jog to acknowledge:



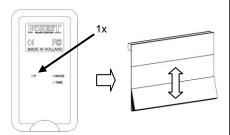
NOTE: if you need to start over, switch off the power and wait at least 20 seconds before switching in the power



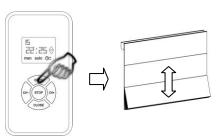
# BS 24V DOUBLE SHAFT MOTOR - 36.4800.0000 BUILD-IN RECEIVER - ELECTRONIC LIMIT SETTING

### **SET UPPER END LIMIT**

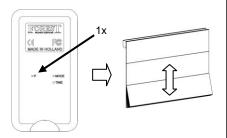
press P2 button once, motor will jog to acknowledge:



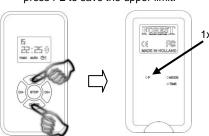
press OPEN button on remote, motor will jog to acknowledge:



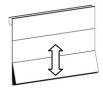
press P2 button once, motor will jog to acknowledge:



adjust desired upper end limit and press P2 to save the upper limit:

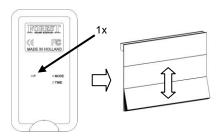


motor will jog to acknowledge:

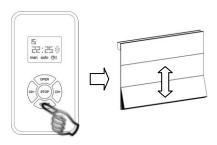


### **SET LOWER END LIMIT**

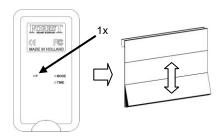
press P2 button once, motor will jog to acknowledge:



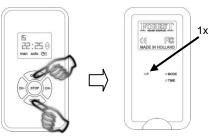
press CLOSE button on remote, motor will jog to acknowledge:



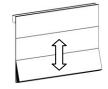
press P2 button once, motor will jog to acknowledge:



adjust desired lower end limit and press P2 to save the lower limit

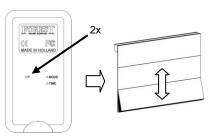


motor will jog to acknowledge:

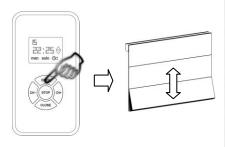


### **DELETE LIMITS**

press P2 button twice, motor will jog to acknowledge:

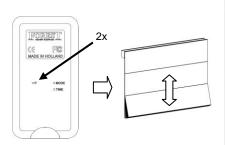


press OPEN button on remote, motor will jog to acknowledge:



### **DELETE ALL MEMORY**

press P2 button twice motor will jog to acknowledge:



press CLOSE button on remote, motor will jog twice to acknowledge

